

# Non-cooperative polymorphic P systems with "finitely representable" regions

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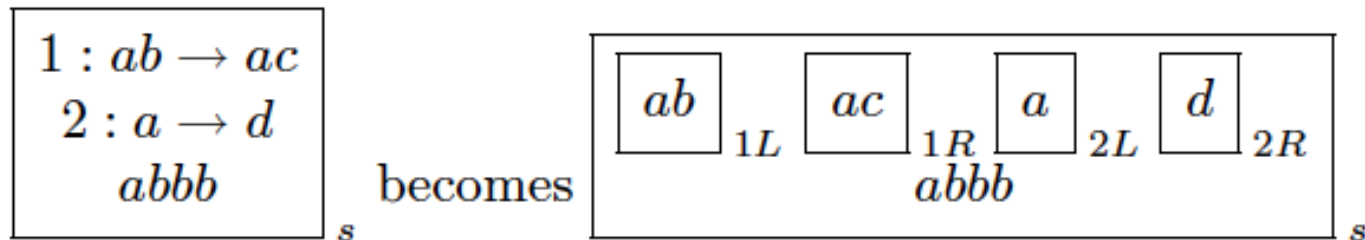


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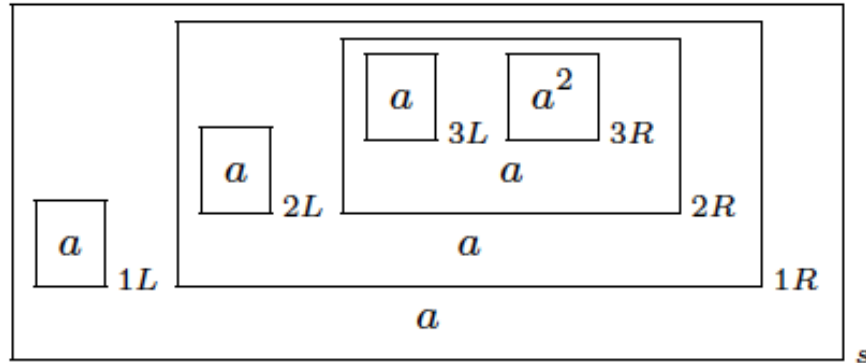


# Polymorphic P systems - The idea

- To manipulate the **rules** during a computation: **represent them as data**



# For example



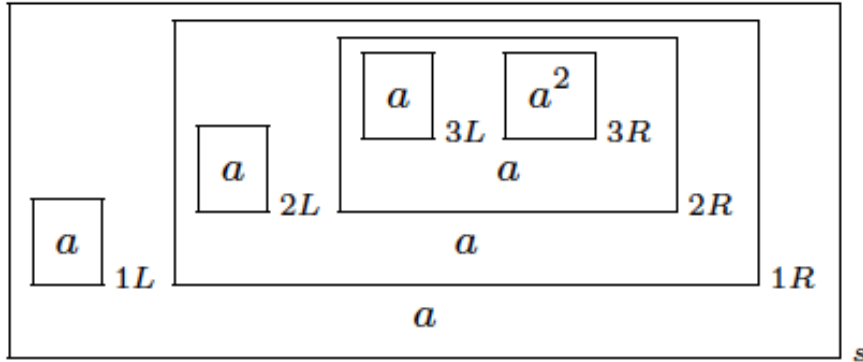
$3 : a \rightarrow a^2$  in  $2R$   
 $2 : a \rightarrow a$  in  $1R$   
 $1 : a \rightarrow a$  in  $s$   
 $\Rightarrow$



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# For example

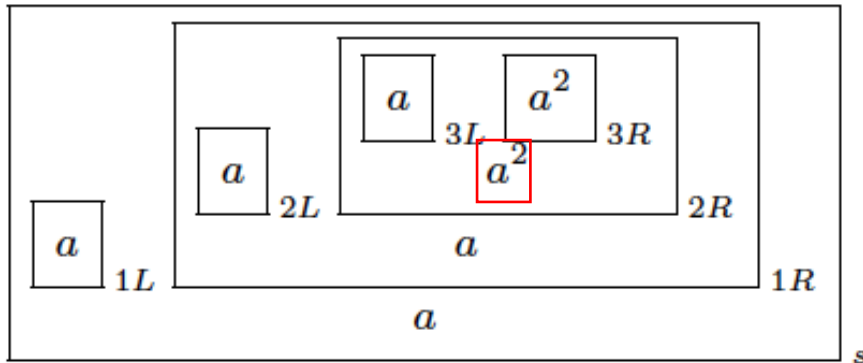


$$3 : a \rightarrow a^2 \text{ in } 2R$$

$$2 : a \rightarrow a \text{ in } 1R$$

$$1 : a \rightarrow a \text{ in } s$$

$\Rightarrow$



$$3 : a \rightarrow a^2 \text{ in } 2R$$

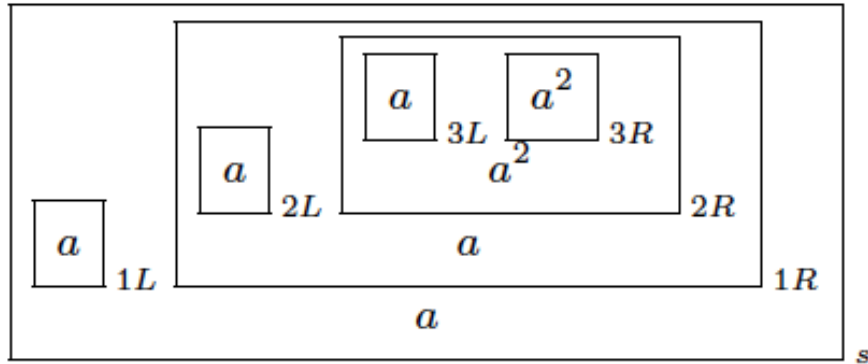
$$2 : a \rightarrow a^2 \text{ in } 1R$$

$$1 : a \rightarrow a \text{ in } s$$

$\Rightarrow$



# For example

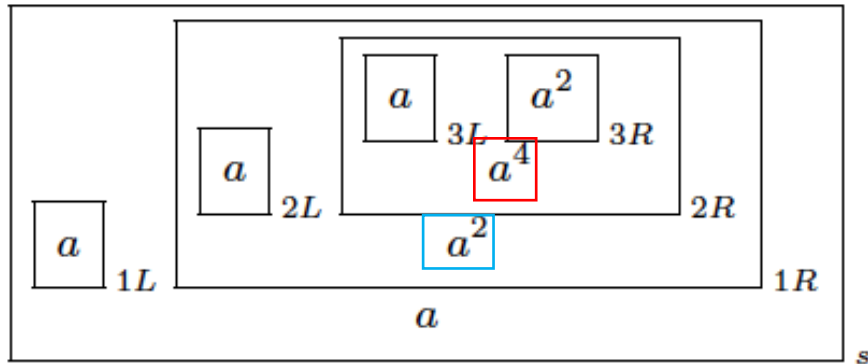


$$3 : a \rightarrow a^2 \text{ in } 2R$$

$$2 : a \rightarrow a^2 \text{ in } 1R$$

$$1 : a \rightarrow a \text{ in } s$$

$\Rightarrow$



$$3 : a \rightarrow a^2 \text{ in } 2R$$

$$2 : a \rightarrow a^4 \text{ in } 1R$$

$$1 : a \rightarrow a^2 \text{ in } s$$

$\Rightarrow$



# Systems with non-cooperative rules

- Artiom Alhazov, Sergiu Ivanov, Yurii Rogozhin: Polymorphic P Systems.  
In: *CMC 2010*, Vol. 6501 of *LNCS*, pp. 81-94, 2010
- Sergiu Ivanov: Polymorphic P Systems with Non-cooperative Rules and No Ingredients.  
In: *CMC 2014*, Vol. 8961 of *LNCS*, pp. 258-273, 2014



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# Non-cooperative polymorphic P systems with limited depth

Theorem:  $PsET0L \subseteq \mathcal{L}(NOP^3(\text{polym}, \text{ncoo}))$ .



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# Systems with finite sets of instances of dynamic rules

- **Non-cooperative** rules → Left-membranes have **finitely many** possible **membrane contents** in any computation  
→ left-membranes are always “**finitely representable**”
- What about “finitely representable” **right-membranes**?



# Finite representability

$$\Pi = (O, T, \mu, w_s, \langle w_{1L}, w_{1R} \rangle, \dots, \langle w_{nL}, w_{nR} \rangle, h_o)$$

- If  $w_h$  is the contents of **region  $h$**  after the  **$j$ -th step** of a computation, and  $w'_h$  can be obtained from  $w_h$  in the **next computational step**:

$$w'_h \in \sigma_{j,h}(w_h)$$

- and  $\sigma_{j,h}^0(w_h) = w_h$ ,  
 $\sigma_{j,h}^{k+1} = \sigma_{j+k,h}(\sigma_{j,h}^k(w_h))$  (set of contents obtainable in  $k+1$  steps)

- $\sigma_{j,h}^* = \bigcup_{k \geq 0} \sigma_{j,h}^k(w_h)$



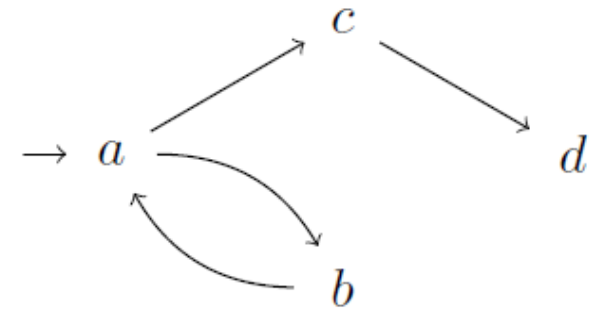
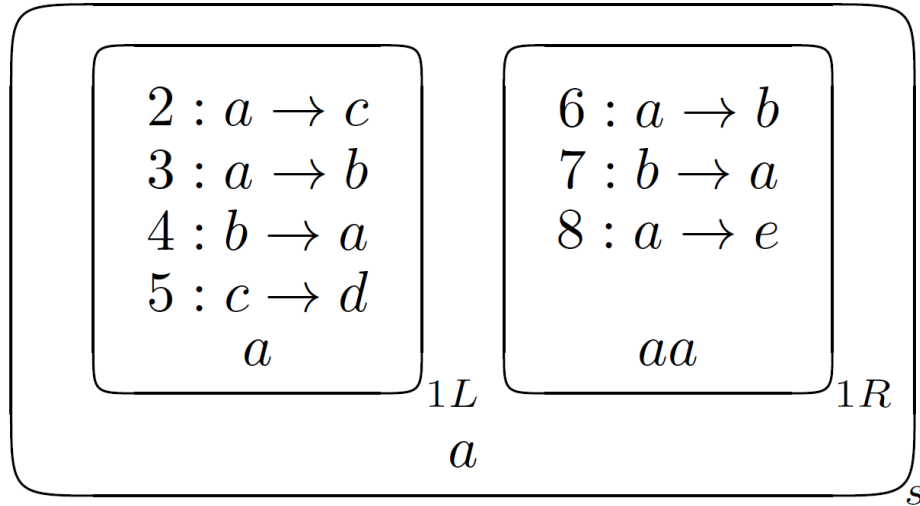
# Finite representability

Region  $h$  is **FIN-representable** if the **set of successor multisets** of the initial contents  $w_h$  of region  $h$  is **finite**.

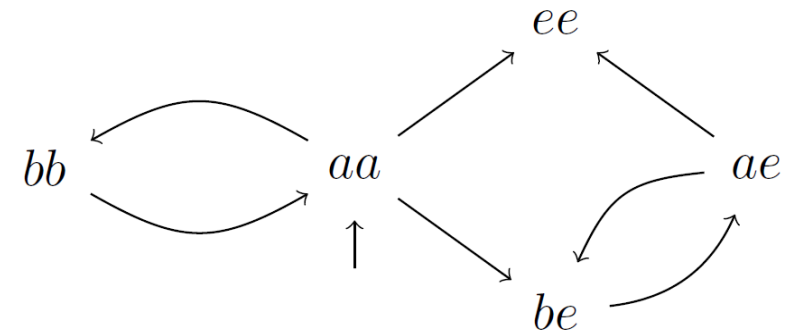
→ if  $\sigma_{0,h}^*(w_h)$  is finite



# FIN-representability, an example



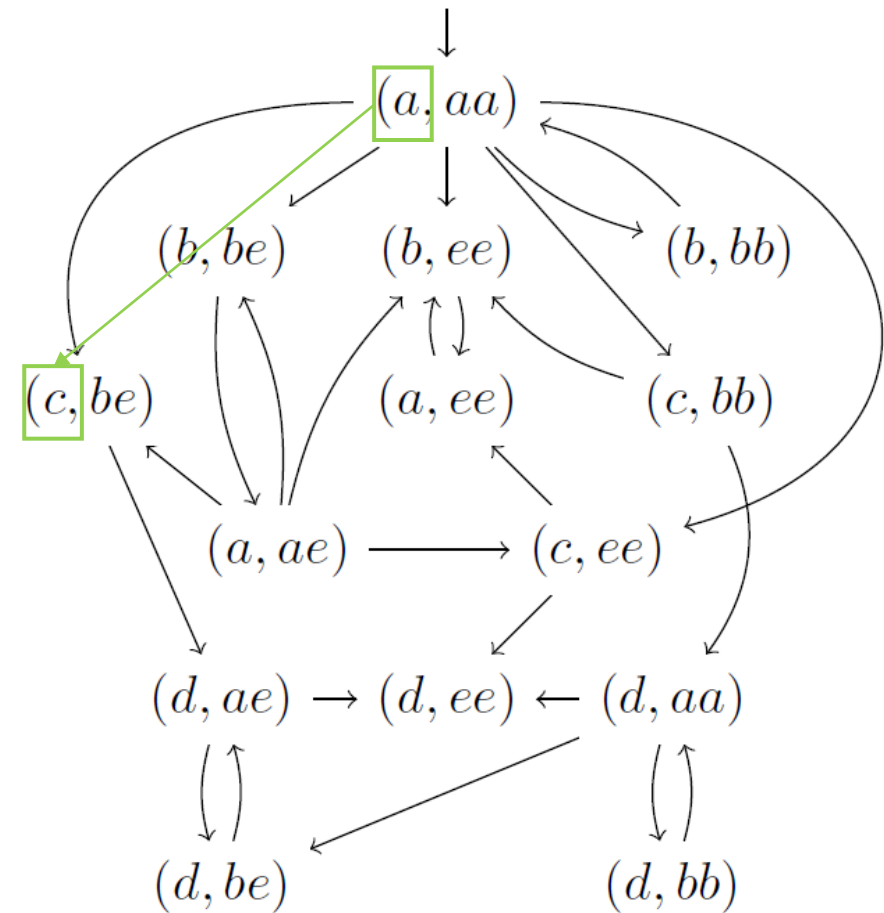
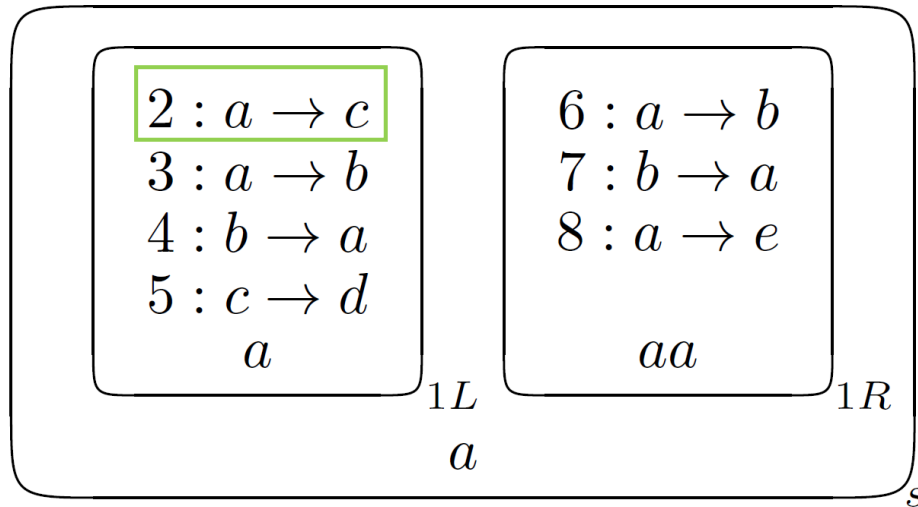
$$\sigma_{0,1L}^*(a) = \{a, b, c, d\}$$



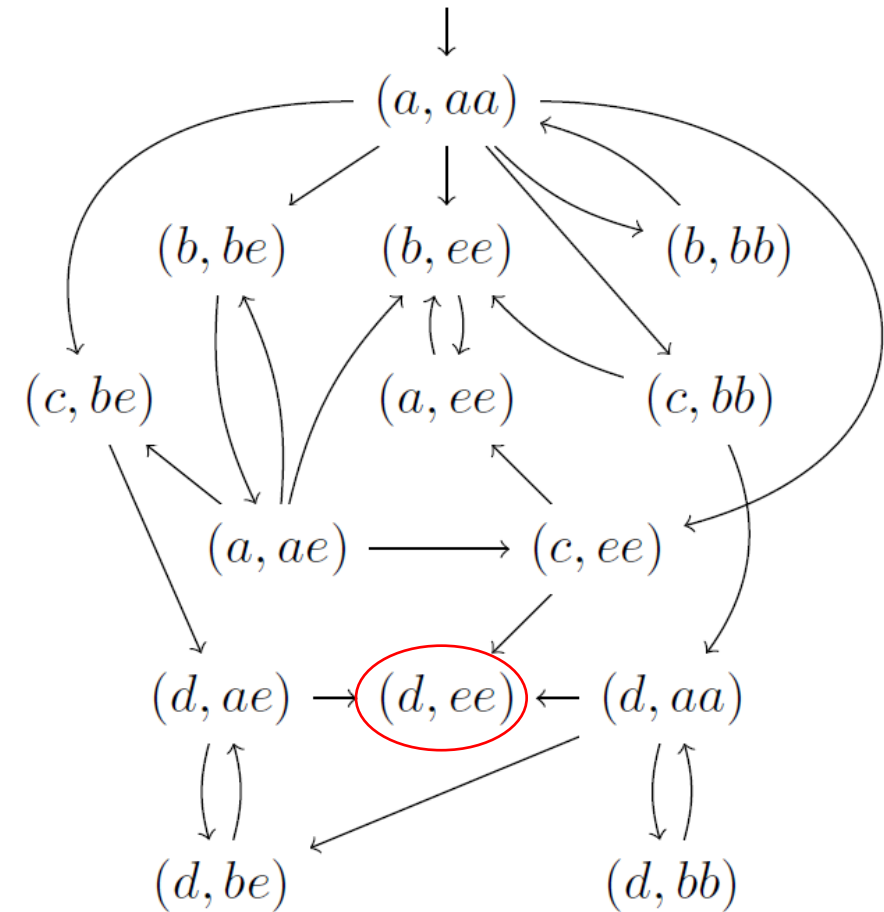
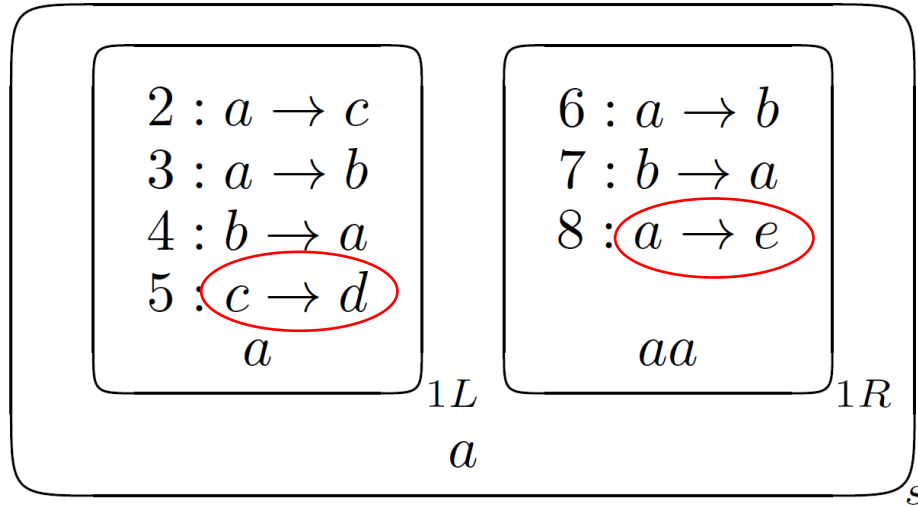
$$\sigma_{0,1R}^*(aa) = \{aa, bb, ae, be, ee\}$$



# FIN-representability, an example



# FIN-representability, an example



**Lemma 2.** *For any polymorphic P system  $\Pi \in NOP(\text{polym}, \text{ncoo}, \text{fin})$ , we can construct a finite transition system  $M_{\Pi}$  which represents the rule configurations of  $\Pi$ .*



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# Proof

$\Pi \in NOP(polym, ncoo, fin)$

$\Pi = (O, T, \mu, w_s, \langle w_{1L}, w_{1R} \rangle, \dots, \langle w_{nL}, w_{nR} \rangle, s)$ , and let  $1L, 1R, \dots, kL, kR$  for some  $k \leq n$  be the labels of those regions which are directly enclosed in the skin membrane.



$M_{1\dots k}$



# Proof

(1) If a membrane labelled by  $h \in \{1L, 1R \dots, nL, nR\}$  is an elementary membrane, then let  $M_h = (Q_h, \bar{q}_h, \delta_h)$ , where

- $Q_h = \{\bar{q}\} = \{(w_h, \emptyset)\}$ , and
- $\delta_h : Q_h \rightarrow 2^{Q_h}$  such that  $\delta_h(\bar{q}_h) = \emptyset$ .





# Proof

(2) If we have already constructed  $M_{iL}, M_{iR}$  for the pair of membranes labelled by  $iL, iR$  for some  $1 \leq i \leq n$ , we construct  $M_i = (R_i, \bar{r}_i, \delta_i)$  to represent the dynamical rule corresponding to this pair of membranes with

- $R_i = \pi_1(Q_{iL}) \times \pi_1(Q_{iR})$  where  $\pi_1$  denotes the first projection of the pairs in  $Q_{iL}, Q_{iR}$ , (that is, the first components of the states, the components which denote the contents of the corresponding region),
- $\bar{r}_i = (w_{iL}, w_{iR})$ , or using the notation with the first projection as above, we might also write that  $\bar{r}_i = (\pi_1(\bar{q}_{iL}), \pi_1(\bar{q}_{iR}))$ , and
- $\delta_i : R_i \rightarrow 2^{R_i}$  such that  $(u'_{iL}, u'_{iR}) \in \delta_i(u_{iL}, u_{iR})$ , if and only if
  - $u'_{iL} \in \delta_{iL}(u_{iL})$  and  $u'_{iR} \in \delta_{iR}(u_{iR})$ , or
  - if  $\delta_{iL}(u_{iL}) = \emptyset$  and  $u'_{iR} \in \delta_{iR}(u_{iR})$  (or if  $\delta_{iR}(u_{iR}) = \emptyset$  and  $u'_{iL} \in \delta_{iL}(u_{iL})$ ) then  $u'_{iL} = u_{iL}$  (or  $u'_{iR} = u_{iR}$ , respectively), and $\delta_i(u_{iL}, u_{iR}) = \emptyset$ , if and only if  $\delta_{iL}(u_{iL}) = \delta_{iR}(u_{iR}) = \emptyset$ .



# Proof

(3) If the membranes that are directly enclosed by the non-elementary membrane (their parent membrane) with label  $h$  are labelled by  $i_1L, i_1R, \dots, i_kL, i_kR$ , and we have already constructed  $M_{i_1}, \dots, M_{i_k}$  for all the pairs  $i_jL, i_jR$ ,  $1 \leq j \leq k$ , then we construct the representation  $M_h$  in two steps.

(3.1) We first construct  $M_{i_1 \dots i_k} = (R_{i_1 \dots i_k}, \bar{r}_{i_1 \dots i_k}, \delta_{i_1 \dots i_k})$  with

- $R_{i_1 \dots i_k} = R_{i_1} \times \dots \times R_{i_k}$ ,
- $\bar{r}_{i_1 \dots i_k} = (\bar{r}_{i_1}, \dots, \bar{r}_{i_k})$ , and
- $\delta_{i_1 \dots i_k} : R_{i_1 \dots i_k} \rightarrow 2^{R_{i_1 \dots i_k}}$  such that  $(r'_{i_1}, \dots, r'_{i_k}) \in \delta_{i_1 \dots i_k}(r_{i_1}, \dots, r_{i_k})$ , if and only if
  - $r'_{i_j} \in \delta_{i_j}(r_{i_j})$  for all  $i_j$ ,  $1 \leq j \leq k$ , or
  - if  $\delta_{i_j}(r_{i_j}) = \emptyset$ , but there is at least one  $i_l$ , such that  $\delta_{i_l}(r_{i_l}) \neq \emptyset$ ,  $1 \leq j, l \leq k$ , then  $r'_{i_j} = r_{i_j}$ , and

$\delta_{i_1 \dots i_k}(r_{i_1}, \dots, r_{i_k}) = \emptyset$ , if and only if,  $\delta_{i_j}(r_{i_j}) = \emptyset$  for all  $i_j$ ,  $1 \leq j \leq k$ .



# Proof

(3.2) Given  $M_{i_1 \dots i_k}$  and the initial multiset  $w_h$ , we can construct  $M_h = (Q_h, \bar{q}_h, \delta_h)$  as

- $Q_h = \sigma_{0,h}^*(w_h) \times R_{i_1 \dots i_k}$ , the direct product of the possible contents of region  $h$  and the possible  $k$ -tuples of rules by the pairs of regions  $i_j L, i_j R$ ,  $1 \leq j \leq k$ ,
- $\bar{q}_h = (w_h, \bar{r}_{i_1 \dots i_k})$ , the pair of the initial contents and the  $k$ -tuple of rules represented by the initial configuration, and
- $\delta_h : Q_h \rightarrow 2^{Q_h}$  such that  $(u'_h, r'_{i_1 \dots i_k}) \in \delta_h(u_h, r_{i_1 \dots i_k})$  if and only if
  - the multiset  $u'_h$  can be obtained from  $u_h$  by the maximal parallel application of the set of rules of  $r_{i_1 \dots i_k}$ , denoted as  $u_h \Rightarrow_{\{r_{i_1}, \dots, r_{i_k}\}} u'_h$  where  $r_{i_1 \dots i_k} = (r_{i_1}, \dots, r_{i_k})$ , and
  - $r'_{i_1 \dots i_k} \in \delta_{i_1 \dots i_k}(r_{i_1 \dots i_k})$ , or if  $\delta_{i_1 \dots i_k}(r_{i_1 \dots i_k}) = \emptyset$ , then  $r'_{i_1 \dots i_k} = r_{i_1 \dots i_k}$ , or
  - if  $r'_{i_1 \dots i_k} \in \delta_{i_1 \dots i_k}(r_{i_1 \dots i_k})$ , but the rules of  $r_{i_1 \dots i_k} = (r_{i_1}, \dots, r_{i_k})$  are not applicable to  $u_h$ , then  $u'_h = u_h$ .



# Proof

If none of the cases above holds, that is, none of the rules of  $r_{i_1 \dots i_k} = (r_{i_1}, \dots, r_{i_k})$  are applicable to  $u_h$ , and  $\delta_{i_1 \dots i_k}(r_{i_1 \dots i_k}) = \emptyset$ , then  $\delta_h(u_h, r_{i_1 \dots i_k}) = \emptyset$ , thus, the state  $(u_h, r_{i_1 \dots i_k})$  is a halting state in  $M_h$ .



# Proof

If  $\Pi = (O, T, \mu, w_s, \langle w_{1L}, w_{1R} \rangle, \dots, \langle w_{nL}, w_{nR} \rangle, s)$  with  $1L, 1R, \dots, kL, kR$ ,  $k \leq n$  being the labels of those regions which are directly enclosed in the skin membrane, and we let  $M_\Pi = M_{1\dots k}$ , then the states of  $M_\Pi$  represent the dynamically changing collections of rules applicable in the skin region, which can change as allowed by the possible transitions of  $M_\Pi$ , in short,  $M_\Pi$  represents the rule configurations of  $\Pi$ .



**Theorem 3.**  $\mathcal{L}(NOP(polym, ncoo, fin)) \subseteq PsET0L$ .

*Proof.* Let  $\Pi = (O, T, \mu, w_s, \langle w_{1L}, w_{1R} \rangle, \dots, \langle w_{nL}, w_{nR} \rangle, s)$  be a polymorphic P system,  $\Pi \in NOP(polym, ncoo, fin)$ , and let us assume (without loss of generality) that the membranes that are directly contained in the skin region are labelled by the labels  $1L, 1R, \dots, kL, kR$ ,  $k \leq n$ . Since both the left- and right-hand membranes  $iL, iR$ ,  $1 \leq i \leq k$ , are FIN-representable, we can construct the transition system  $M_\Pi = (R_\Pi, \bar{r}_\Pi, \delta_\Pi) = M_{1\dots k} = (R_{1\dots k}, \bar{r}_{1\dots k}, \delta_{1\dots k})$  as described in the proof of Lemma 2.

Now, based on  $M_\Pi$ , we construct an ET0L system  $G = (V, T, U, w)$ , where  $V$  contains the alphabet,  $T$  the terminal alphabet with  $T \subseteq V$ ,  $w$  is the initial string, and  $U$  is a set of tables,  $U = (P_1, P_2, \dots, P_m)$  containing at most three tables for each state of  $M_\Pi$  and one additional table.

⋮



# A characterization of $PsETOL$

Theorem:  $\mathcal{L}(NOP(polym, ncoo, fin)) \subseteq PsETOL$ .

Corollary:  $\mathcal{L}(NOP(polym, ncoo, fin)) = PsETOL$ .



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Thank you for your attention!



**Example 4.** Let us construct the representation  $M_{\Pi} = M_1$  for the P system of Example 3. Starting with the elementary membranes, we get  $M_{2L} = (\{(a, \emptyset)\}, (a, \emptyset), \delta_{2L})$ ,  $M_{2R} = (\{(c, \emptyset)\}, (c, \emptyset), \delta_{2R})$  such that  $\delta_{2L}(a, \emptyset) = \delta_{2R}(c, \emptyset) = \emptyset$ , and  $M_2 = (R_2, \bar{r}_2, \delta_2)$  with  $R_2 = \{a\} \times \{c\} = \{(a, c)\}$ ,  $\bar{r}_2 = (a, c)$ , and  $\delta_2(a, c) = \emptyset$ . Similarly, we can construct  $M_i$  for all  $i$ ,  $2 \leq i \leq 8$ , which all have a similar structure.

Now, given the transition systems  $M_2, \dots, M_5$  we construct  $M_{1L}$  as follows. We start with the construction of  $M_{2\dots 5} = (R_{2\dots 5}, \bar{r}_{2\dots 5}, \delta_{2\dots 5})$  as

- $R_{2\dots 5} = \{((a, c), (a, b), (b, a), (c, d))\}$ ,
- $\bar{r}_{2\dots 5} = ((a, c), (a, b), (b, a), (c, d))$ , and
- $\delta_{2\dots 5}((a, c), (a, b), (b, a), (c, d)) = \emptyset$ .

If denote the rules by  $r_2 = (a, c)$ ,  $r_3 = (a, b)$ ,  $r_4 = (b, a)$ , and  $r_5 = (c, d)$ , then  $M_{1L} = (Q_{1L}, \bar{q}_{1L}, \delta_{1L})$  is as follows.

The set of possible states is  $Q_{1L} = \{a, b, c, d, e\} \times \{(r_2, r_3, r_4, r_5)\}$ , that is,

$$Q_{1L} = \{(a, (r_2, r_3, r_4, r_5)), (b, (r_2, r_3, r_4, r_5)), (c, (r_2, r_3, r_4, r_5)), \\ (d, (r_2, r_3, r_4, r_5)), (e, (r_2, r_3, r_4, r_5))\},$$

the initial state is  $\bar{q}_{1L} = (a, (r_2, r_3, r_4, r_5))$ , and the transition mapping is defined as

$$\begin{aligned} \delta_{1L}(a, (r_2, r_3, r_4, r_5)) &= \{(c, (r_2, r_3, r_4, r_5)), (b, (r_2, r_3, r_4, r_5))\}, \\ \delta_{1L}(c, (r_2, r_3, r_4, r_5)) &= \{(d, (r_2, r_3, r_4, r_5))\}, \\ \delta_{1L}(b, (r_2, r_3, r_4, r_5)) &= \{(a, (r_2, r_3, r_4, r_5))\}, \\ \delta_{1L}(d, (r_2, r_3, r_4, r_5)) &= \emptyset. \end{aligned}$$



With a similar construction, we can construct  $M_{1R} = (Q_{1R}, \bar{q}_{1R}, \delta_{1R})$  as

$$Q_{1R} = \{(aa, (r_6, r_7, r_8)), (bb, (r_6, r_7, r_8)), (be, (r_6, r_7, r_8)), \\ (ae, (r_6, r_7, r_8)), (ee, (r_6, r_7, r_8))\},$$

where  $r_6 = (a, b)$ ,  $r_7 = (b, a)$ , and  $r_8 = (a, e)$ . Further,  $\bar{q}_{1R} = (aa, (r_6, r_7, r_8, r_9))$ , and

$$\delta_{1R}(aa, (r_6, r_7, r_8)) = \{(bb, (r_6, r_7, r_8)), (be, (r_6, r_7, r_8)), (ee, (r_6, r_7, r_8))\},$$

$$\delta_{1R}(bb, (r_6, r_7, r_8)) = \{(aa, (r_6, r_7, r_8))\},$$

$$\delta_{1R}(be, (r_6, r_7, r_8)) = \{(ae, (r_6, r_7, r_8))\},$$

$$\delta_{1R}(ae, (r_6, r_7, r_8)) = \{(be, (r_6, r_7, r_8)), (ee, (r_6, r_7, r_8))\},$$

$$\delta_{1R}(ee, (r_6, r_7, r_8)) = \emptyset.$$



Now, given  $M_{1L}$  and  $M_{1R}$  we can construct  $M_1 = M_{\Pi}$  as  $M_1 = (R_1, \bar{r}_1, \delta_1)$  where

$$R_1 = \pi_1(Q_{1L}) \times \pi_1(Q_{1R}) = \{a, b, c, d\} \times \{aa, bb, be, ae, ee\},$$

is the set of states,  $\bar{r}_1 = (a, aa)$  is the initial state, and

$$\delta_1(a, aa) = \{(b, bb), (b, be), (b, ee), (c, bb), (c, be), (c, ee)\},$$

$$\delta_1(b, bb) = \{(a, aa)\},$$

$$\delta_1(b, be) = \{(a, ae)\},$$

$$\delta_1(b, ee) = \{(a, ee)\},$$

$$\delta_1(c, bb) = \{(d, aa)\},$$

$$\delta_1(c, be) = \{(d, ae)\},$$

$$\delta_1(c, ee) = \{(d, ee)\},$$

$$\delta_1(a, ae) = \{(c, be), (c, ee), (b, be), (b, ee)\}.$$

$$\delta_1(a, ee) = \{(c, ee), (b, ee)\},$$

$$\delta_1(d, aa) = \{(d, ee), (d, be), (d, bb)\},$$

$$\delta_1(d, ae) = \{(d, ee), (d, be)\},$$

$$\delta_1(d, bb) = \{(d, aa)\},$$

$$\delta_1(d, be) = \{(d, ae)\},$$

$$\delta_1(d, ee) = \emptyset.$$

